LB1843V

Monolithic Linear IC

Low-saturation, current-controlled bidirectional motor driver

ON Semiconductor®

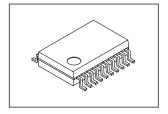
http://onsemi.com

Overview

The LB1843V is a low-saturation bidirectional motor driver with output current limitation and detection functions. This design is ideal for controlling the loading motor in a video camera.

Function

- Output current limiter and detector built in.
- Low-saturation voltage bidirectional bridge circuit built in: VOsat = 0.40 V typ. at 400 mA.
- Practically no current drain (0.1 µA or less) in standby mode.
- Input-linked reference voltage built in .
- Thermal shutdown circuit built in.
- Requires little space, since few external components are needed and the IC is contained in a small SSOP-20 package



SSOP20 (225mil)

Specifications

Absolute Maximum Ratings at Ta = 25°C

| Parameter | Symbol | Conditions | Ratings | Unit |
|-----------------------------|---------------------|--------------------------|-------------|------|
| Maximum supply voltage | V _{CC} max | | 10.5 | ٧ |
| Maximum output current | Im max | | 800 | mA |
| Applied Input voltage | V _{IN} | | -0.3 to +10 | ٧ |
| Allowable power dissipation | Pd max | With board (50x35x1.6mm) | 800 | mW |
| Operating temperature | Topr | | -20 to +80 | °C |
| Storage temperature | Tstg | | -40 to +150 | °C |

Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.

Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

Recommended Operating Conditions at Ta = 25°C

| Parameter | Symbol Conditions | 0 1111 | Ratings | | | |
|---------------------------|-------------------|--------|---------|-----|----------------------|----|
| | | min | typ | max | Unit | |
| Supply voltage | V _{CC} | | 3.0 | | 9.0 | V |
| V _M voltage | ٧ _M | | 2.2 | | V _{CC} | V |
| High-level input voltage | V _{IH} | | 3.0 | | 9.0 | V |
| Low-level input voltage | V _{IL} | | -0.3 | | +0.7 | V |
| LIR input voltage | V _{LIR} | | 0.5 | | V _{CC} -1.0 | V |
| Output current limitation | l limit | | 50 | | 350 | mA |

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

ORDERING INFORMATION

See detailed ordering and shipping information on page 10 of this data sheet.

Electrical Characteristics at Ta = 25°C, $V_{CC} = 7.2V$

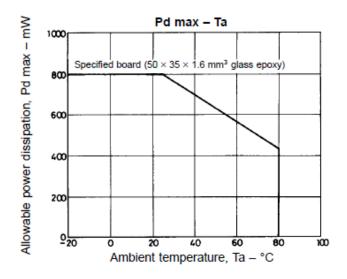
| December | 0 | O colling of | | Ratings | | |
|---------------------------|---------------------|---|------|---------|------|------|
| Parameter | Symbol Conditions | | min | typ | max | Unit |
| Supply current | I _{CC} 0 | During standby | | 0.1 | 10 | μА |
| | I _{CC} 1 | During bidirectional operation, no load | | 9 | 13 | mA |
| | l _{CC} 2 | During braking | | 12 | 18 | mA |
| Output saturation voltage | V _{sat} 1 | I _{OUT} = 200mA (upper side + lower side) | | 0.20 | 0.30 | V |
| (upper side + lower side) | V _{sat} 2 | I _{OUT} = 400mA (upper side + lower side) | | 0.40 | 0.60 | V |
| Reference voltage | V _{ref} | I _V ref = 1mA | 1.85 | 2.0 | 2.15 | V |
| Set output current | llimit | Resistance between V_{CC} and V_{M} = 1Ω , when LIR = $2V$ | 165 | 185 | 205 | mA |
| Input current | I _{IN} | V _{IN} = 5V | | 90 | 150 | μΑ |
| RD saturation voltage | V _{RD} sat | I _O = 1mA | | | 0.3 | V |

Output current limit is determined by the following equation (Rf is the sensing resistance between V_{CC} and V_{M}):

I limit = V_{LIR} / 10Rf (A)

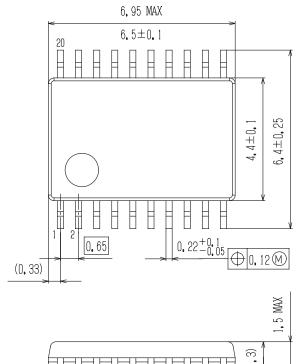
The input range for V_{LIR} is 0.5 to $V_{\text{CC}}-1.0(\text{V})$

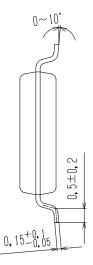
Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

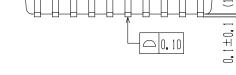


Package Dimensions

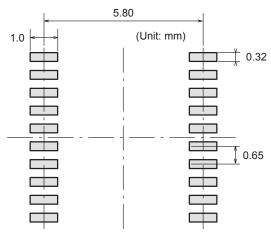
SSOP20 (225mil) CASE 565AN ISSUE A







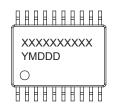
SOLDERING FOOTPRINT*



NOTE: The measurements are not to guarantee but for reference only.

*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

GENERIC MARKING DIAGRAM*



XXXXX = Specific Device Code

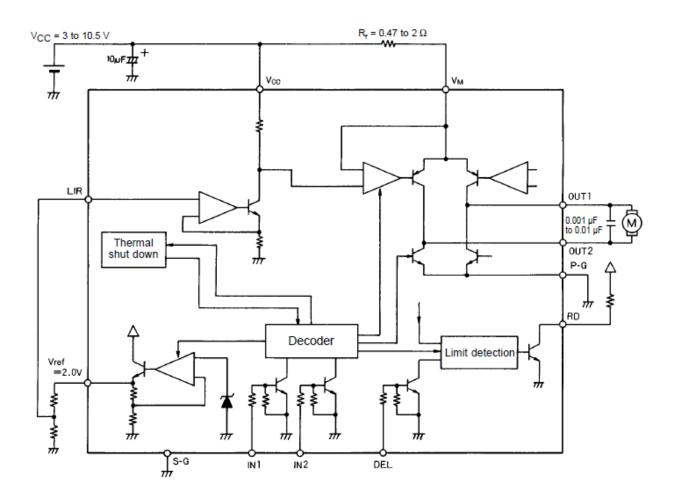
Y = Year

M = Month

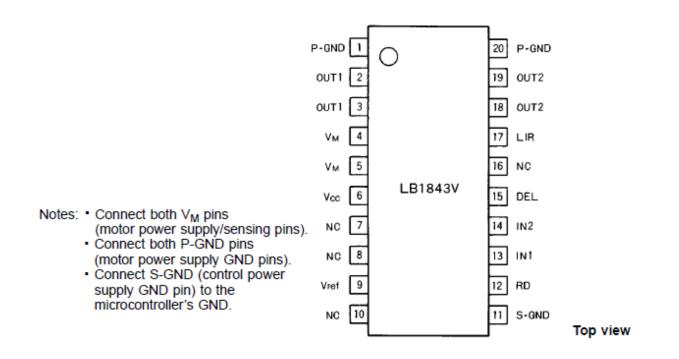
DDD = Additional Traceability Data

^{*}This information is generic. Please refer to device data sheet for actual part marking. Pb–Free indicator, "G" or microdot " ■", may or may not be present.

Block Diagram and Sample Application Circuit



Pin Assignment



Pin Functions

| Pin Funct Pin No. | Pin name | Pin Function | Equivalent Circuit |
|----------------------|--------------------|---|------------------------------|
| 13 | IN1 | Control signal input pin | ┌────○ VCC |
| 14 | IN2 | Control signal input pin | 50K 80K 4K 0 S-GND |
| 15 | DEL | Control signal input pin | O VCC |
| | | | 62K 82K 82K O S-GND |
| 4,5 2,3 18,19 | VM OUT1 OUT2 | Output current detect pin Out pin Out pin | VM |
| | | | O P-GND |

Continued on next page.

| Continued from pr | receding nage | | |
|-------------------|-----------------|-------------------------------|--------------------------|
| 9 | Vref | Reference voltage output pin | |
| | | | VCC 0 5.6K 10K S-GNDO |
| 12 | RD | Lock detect signal output pin | 12K S-GND |
| 17 | LIR | Output current setting pin | VCC O |
| | | Davier averthood to the | |
| 6 | V _{CC} | Power supply voltage pin | |
| 11 | S-GND P-GND | Signal ground pin | |
| 1,20 | | Power ground pin | |
| 7,8,10,16 | NC | No connect | |

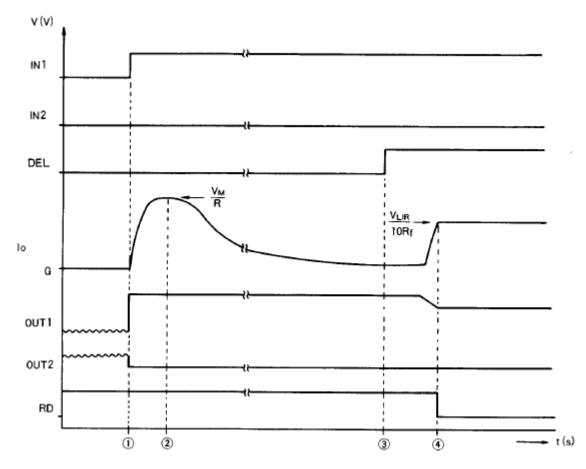
Truth Table

| Input | | Output | | Mada |
|-------|-----|--------|------|---------|
| IN1 | IN2 | OUT1 | OUT2 | Mode |
| L | L | Off | Off | Standby |
| Н | L | Н | L | Forward |
| L | Н | L | Н | Reverse |
| Н | Н | L | L | Brake |

Output Current Limitation and Detector Output

| DEL | OUT output | RD |
|-----|------------|-----|
| | Limit | L |
| Н | Non-limit | Off |
| L | Saturated | Off |

Sample Application Timing Chart



Sample application timing chart

- 1) Connect a DC motor (RL = R) between OUT1 and OUT2, and with the RD pin pulled up, input a forward rotation signal (IN1 = high, IN2 = low).
 - Because the output is used in the saturated state at startup, set the DEL input to low.
- 2) The DC motor starts up, and the startup current (IST = VM/R) flows to the motor.
- 3) The DC motor rotates in the normal state. At this point, set the DEL input to high.
- 4) If the DC motor locks, the motor current IM increases to the point of Ilimit (= VLIR/(10Rf)), the output current limiter operates to limit the output current. At the same time, RD is output low from the set current detection circuit.

Reference voltage (Vref)

The Vref output is linked to the input; if either IN1 or IN2 is high, the reference voltage is output.

Output current limiter

The schematic for the output current limiter is shown below.

The output set current is set according to the reference voltage VLIR applied to the LIR pin. When VLIR is applied, 1/10 of that voltage is generated at both ends of RS in the diagram; this voltage is input on the positive (+) side of the current setting amplifier.

The motor current IM generates voltage equal to (IM 'Rf) at both ends of the external resistor Rf. This voltage is input to the negative (–) side of the same amplifier, and the differential amplifier functions and the output transistors are driven so that these inputs become equal.

The set current value in this instance is determined by the following equation:

Ilimit = VLIR/(10Rf) [A]

Set current detector

(1) When DEL = high

If the motor current IM has not reached the set current Ilimit, the input voltage on the negative (–) side of the amplifier is greater than the input voltage on the positive (+) side. As a result, the drive current increases and the output PNP transistors reach the saturation state. If this state is detected, the detection signal is sent to the set current detector, and the RD output goes high.

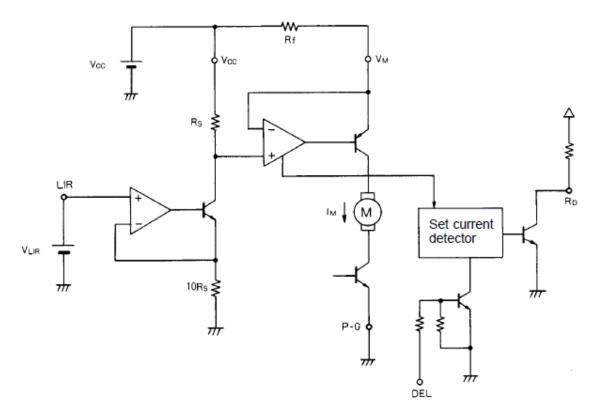
If the motor current IM reaches the set current Ilimit, the output PNP transistor enters the controlled state, and the RD output goes low.

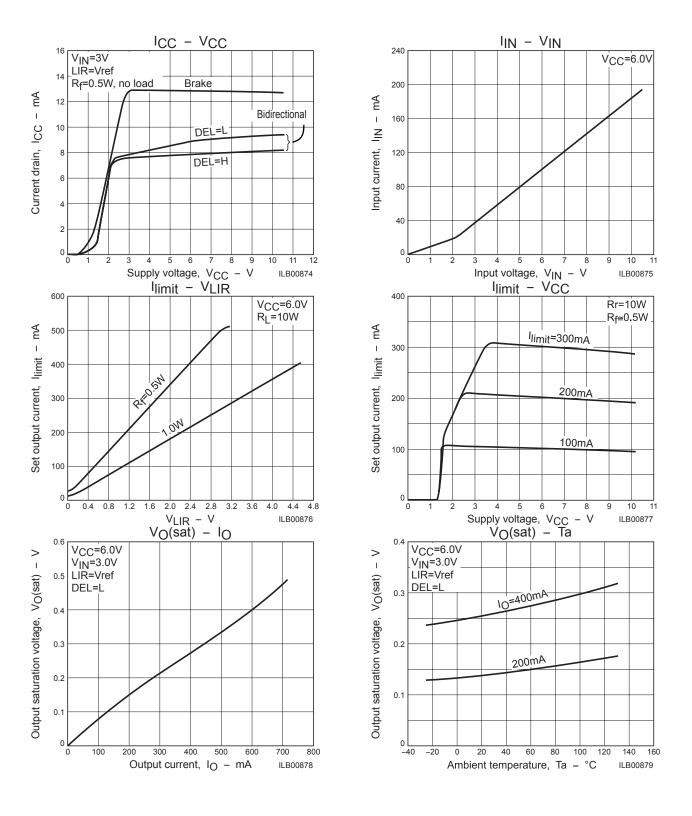
(2) When DEL = low

Because the operation of the current setting amplifier is cancelled when a low signal is input to the DEL pin, the output PNP transistors reach the saturation state and the RD output goes high, just as in the case described above. The following table summarizes the states described above.

| DEL | OUT output | RD |
|-----|------------|-----|
| н | Limit | |
| | Non-limit | Off |
| L | Saturated | Off |

Output Current Limiter and Set Current Detector Block Diagram





LB1843V

ORDERING INFORMATION

| Device | Package | Shipping (Qty / Packing) |
|---------------|---|--------------------------|
| LB1843V-MPB-E | SSOP20 (225mil) (Pb-Free / Halogen Free) | 70 / Fan-Fold |
| LB1843V-TLM-E | SSOP20 (225mil) (Pb-Free / Halogen Free) | 2000 / Tape & Reel |

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